L Number	Hits	Search Text	DB	Time stamp
8	355	(Manus with Henry) (David with Sandoz) (David with Clarke)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/01 15:12
9	3	((Manus with Henry) (David with Sandoz) (David with Clarke)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/01 15:13
10	47) and seva ((Manus with Henry) (David with Sandoz) (David with Clarke)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/01 15:13
11	16) and sensor ((Manus with Henry) (David with Sandoz) (David with Clarke)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/01 15:18
) and ((sensing sensor detect sense detection detector detecting) same (fusion fused fuse fusing integrate integration integrating))		
12	127517	((sensing sensor detect sense detection detector detecting) same (fusion fused fuse fusing integrate integration integrating))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/06/01 15:27
13	3	((sensing sensor detect sense detection detector detecting) same (fusion fused fuse fusing integrate integration integrating)) and seva	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/06/01 15:18
14	45	detector detecting) same (fusion fused fuse fusing integrate integration integrating)) and ((self near (validating	USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/06/01 15:21
15	33	validate validation)) seva) (((sensing sensor detect sense detection detector detecting) same (fusion fused fuse fusing integrate integration integrating)) and ((self near (validating validate validation)) seva)) not(((Manus with Henry) (David with Sandoz) (David with Clarke)	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/01 15:19
16	28) and sensor)) ((sensing sensor detect sense detection detector detecting) same (fusion fused fuse fusing integrate integration integrating)) and ((self near (validating validate validation)) seva) and reference and status	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/01 15:22

		·		
17	25	((sensing sensor detect sense detection	USPAT;	2004/06/01
		detector detecting) same (fusion fused	US-PGPUB;	15:23
	1	fuse fusing integrate integration	EPO; JPO;	
		integrating)) and ((self near (validating	DERWENT;	
		validate validation)) seva) and	IBM_TDB	
		reference and ((sensing sensor detect	_	
		sense detection detector detecting		
		process) with status)		
18	24	((sensing sensor detect sense detection	USPAT;	2004/06/01
		detector detecting) same (fusion fused	US-PGPUB;	15:28
		fuse fusing integrate integration	EPO; JPO;	
		integrating)) and ((self near (validating	DERWENT;	
		validate validation) near (sensing sensor	IBM TDB	
		detect sense detection detector		
		detecting) seva) and reference and		
		((sensing sensor detect sense detection		
		detector detecting process) with status)		
19	4962		USPAT;	2004/06/01
10	1302	detector detecting) same (fusion fused	US-PGPUB;	15:28
		fuse fusing integrate integration	EPO; JPO;	
		integrating)) and (process with (monitor	DERWENT;	1
		monitoring))	IBM TDB	
20	24	1	USPAT;	2004/06/01
20	27	detector detecting) same (fusion fused	US-PGPUB;	15:28
		fuse fusing integrate integration	EPO; JPO;	13.23
		integrating)) and ((self near (validating	DERWENT;	
		validate validation near (sensing sensor	IBM TDB	
		detect sense detection detector	1511_155	1
		detecting) seva and reference and	İ	
		((sensing sensor detect sense detection		
		detector detecting process) with status)		
	1	and (process with (monitor monitoring))	USPAT;	2004/06/01
21	13	1 1 = = = = = 2	US-PGPUB;	15:29
		detector detecting) same (fusion fused	EPO; JPO;	13.29
	·	fuse fusing integrate integration	DERWENT;	
		integrating)) and ((self near (validating	IBM TDB	
		validate validation) near (sensing sensor	1 101 100	
		detect sense detection detector	[1
		detecting)) seva) and reference and		
		((sensing sensor detect sense detection		
		detector detecting process) with status)		
		and (process near (monitor monitoring))		